AUTOMOTIVE CURRENT TRANSDUCER OPEN LOOP TECHNOLOGY
HAH1BVW-SD08

Introduction

The HAH1BVW family is for the electronic measurement of DC, and low frequency current in high power and low voltage automotive
applications with galvanic separation between the primary circuit (high power) and the secondary circuit (electronic circuit).

The HAH1BVW family gives you the choice of having different current measuring ranges in the same housing.

Features

- Ratiometric transducer
- Open Loop transducer using the Hall effect
- Low voltage application
- Unipolar +5 V DC power supply
- Primary current measuring range ±1200 A (high range) ±350 A (low range)
- Maximum RMS primary admissible current: defined by busbar to have T < +150 °C
- Operating temperature range: −40 °C < T < 125 °C
- Output voltage: full ratio-metric (in sensitivity and offset).

Special feature

- Dual output.

Advantages

- Excellent accuracy
- Very good linearity
- Very low thermal offset drift
- Very low thermal sensitivity drift
- Galvanic separation
- Non intrusive solution.

Automotive applications

- Battery Management.

Principle of HAH1BVW Family

The open loop transducers uses a Hall effect integrated circuit. The magnetic flux density B, contributing to the rise of the Hall voltage, is generated by the primary current I_P to be measured.
The current to be measured I_P is supplied by a current source i.e. battery or generator (Figure 1).
Within the linear region of the hysteresis cycle, B is proportional to:

$$B\,(I_P) = a \times I_P$$

The Hall voltage is thus expressed by:

$$V_H = (c_H\,/\,d) \times I_H \times a \times I_P$$

Except for I_P, all terms of this equation are constant.
Therefore:

$$V_H = b \times I_P$$

a	constant
b	constant
c_H	Hall coefficient
d	thickness of the Hall plate
I_H	current across the Hall plates

The measurement signal V_H amplified to supply the user output voltage or current.
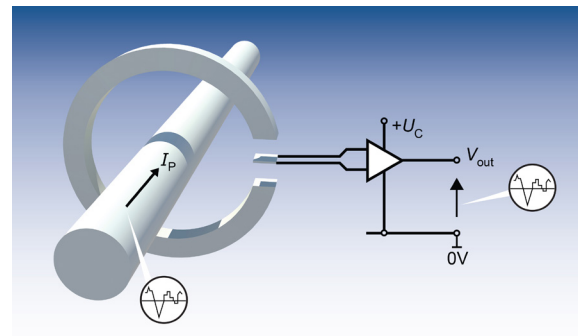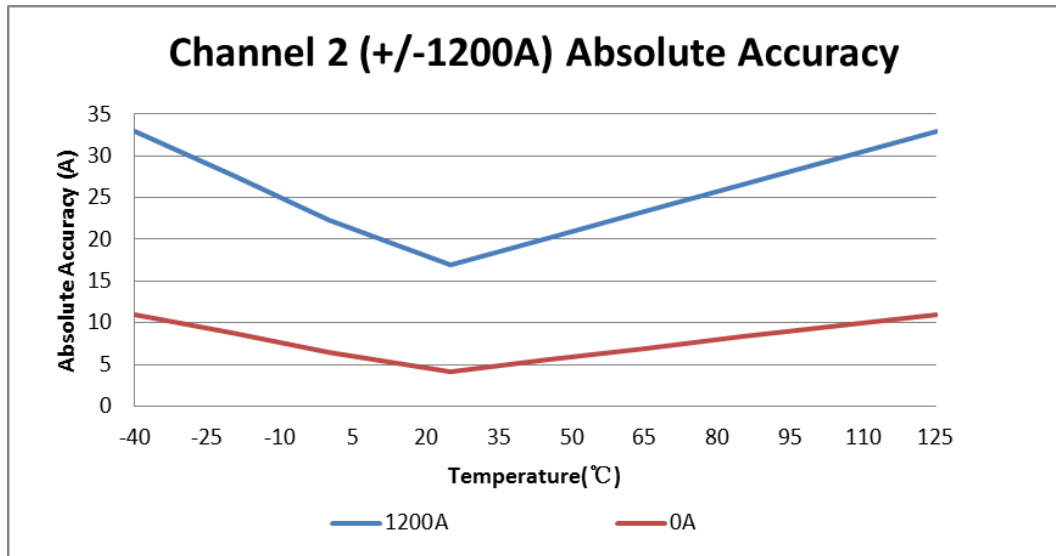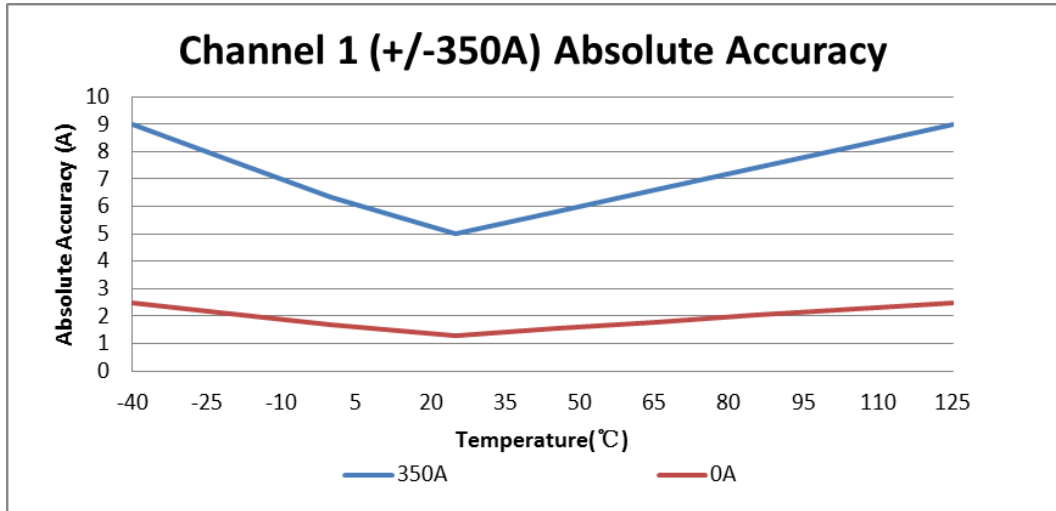

Fig. 1: Principle of the open loop transducer.

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Dimensions HAH1BVW SD08 (in mm)

NOTES
1– Sensor mates with TYCO Connector P/N 1473672–1.
2– Case material : PBT-GF30% glass reinforced (UL94 V0 - CTI=200).
3– Insert material : BRASS type UNS C36000.
4– Terminals material : CuZn33 / C26800.
5– Plating : Sn or Au plating finished.
6– Mass (±5%) : 57 gr .
7– Color : Black.
8– Use M4 NUT according to ISO 4032.
9– Creepage dist. : 5.2 mm / Clearance : 4.9 mm.
10– Current range : ± 200A to ± 1400A.
11– Fundamental tolerances in accordance with ISO system (JS14):

	<=3mm	3to6	6to10	10to18	18to30	30to50	50to80
Quality 14(µm)	250	300	360	430	520	620	740

Drawing for information only

Mechanical characteristics

- Plastic case — PBT GF 30
- Magnetic core — Iron silicon alloy
- Mass — 57 g
- Electrical terminal coating — Brass tin plated

Mounting recommendation

- Connector type — AMP 1473672-1

Electronic schematic

Components list		BV version
IC	Hall sensor ASIC	
C1	Decoupling capacitor	68 nF
C2	Decoupling capacitor	100 nF

Pin out	
A	V_{out} Low range
B	Ground
C	U_c (5 V)
D	V_{out} High range

Remarks

- V_{out} > 2.5 when I_P flows in the direction of the arrow.

System architecture (example)

R_L > 10 kΩ optional resistor for signal line diagnostic

V_{out}	Diagnostic
Open circuit	V_{IN} ≤ 0.15 V
Short GND	V_{IN} ≤ 0.15 V

C_L ≤ 100 nF EMC protection
RC Low pass filter EMC protection (optional)

Absolute ratings (not operating)

Parameter	Symbol	Unit	Specification			Conditions
			Min	Typical	Max	
Maximum supply voltage	$U_{C\,max}$	V			14	
Maximum reverse supply voltage	$U_{C\,max}$	V	−14			
Maximum output Voltage	$V_{out\,max}$	V	−14		14	V_{out} Reverse / Forward voltage
Maximum output Current	$I_{out\,max}$	mA	−10		10	
Ambient storage temperature	T_S	°C	−40		125	
Electrostatic discharge voltage (HBM)	U_{ESD}	kV			8	
Maximum admissible vibration (random RMS)	γ_{max}	m·s^{-2}			96.6	10 to 2000 Hz, −40 °C to 125 °C
RMS voltage for AC insulation test	U_d	kV			2.5	50 Hz, 1 min
Creepage distance	d_{Cp}	mm	4.85			
Clearance	d_{Cl}	mm	4.85			
Comparative traking index	CTI		PLC3 (175 V - 250 V)			

Operating characteristics in high/low range (I_{PN})

Parameter	Symbol	Unit	Specification			Conditions
			Min	Typical	Max	
Electrical Data						
Primary current, measuring range, high range	I_{PM}	A	−1200		1200	
Primary current, measuring range, low range	I_{PN}	A	−350		350	
Supply voltage	U_C	V	4.5	5	5.5	
Ambient operating temperature	T_A	°C	−40		125	
Output voltage	V_{out}	V	$V_{out} = (U_C/5) \cdot (V_o + G \cdot I_P)$			
Sensitivity high range	G	mV/A		1.67		@ T_A = 25 °C
Sensitivity low range	G	mV/A		5.71		@ T_A = 25 °C
Offset voltage	V_O	V		2.5		
Output resolution		mV		2.5		
Output clamping high voltage	V_{SZ}		4.74	4.75		@ U_C = 5 V
Output clamping low voltage	V_{SZ}			0.25	0.26	@ U_C = 5 V
Current consumption	I_C	mA		14		@ T_A = 25 °C, @ U_C = 5 V
					20	
Load resistance	R_L	KΩ	10			@ T_A = 25 °C
Output internal resistance	R_{out}	Ω		1		@ T_A = 25 °C
					10	
Performance Data						
Ratiometricity error	ε_r	%		± 0.2		
Sensitivity error	ε_G	%		± 1		@ T_A = 25 °C
Electrical offset voltage	V_{OE}	mV		± 2.5		@ T_A = 25 °C, @ U_C = 5 V
Magnetic offset voltage	V_{OM}	mV		± 2		@ U_C = 5 V, @ T_A = 25 °C
Linearity error	ε_L	%	- 1		1	% of full scale
Average temperature coefficient of V_{OE}	$TCV_{OE\,AV}$	mV/°C		± 0.04		
Average temperature coefficient of G	TCG_{AV}	%/°C		± 0.02		
Step response time @ 90 %	t_r	ms			10	
Frequency bandwidth	BW	Hz		70		@ - 3 dB
Peak-to-peak noise voltage	$V_{no\,pp}$	mV			10	DC to 1 MHz
Output RMS noise voltage	$V_{no\,rms}$	mV			1.6	
Start-up time	t_{start}	ms			1	
Setting time after overload	t_s	ms			10	

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Channel 1 (+/-350A) Absolute Accuracy

Channel 2 (+/-1200A) Absolute Accuracy

Temperature (°C)	Channel1 Overall Accuracy					
	Accuracy at ±350A			Accuracy at 0A		
−40	9A	51.39 mV	2.57 %	2.5A	14.28 mV	0.71 %
25	5A	28.55 mV	1.43 %	1.3A	7.423 mV	0.37 %
125	9A	51.39 mV	2.57 %	2.5A	14.28 mV	0.71 %

Temperature (°C)	Channel2 Overall Accuracy					
	Accuracy at ±1200A			Accuracy at 0A		
−40	33A	55.11 mV	2.75 %	11A	18.37 mV	0.92 %
25	17A	28.39 mV	1.42 %	4.2A	7.014 mV	0.35 %
125	33A	55.11mV	2.75 %	11A	18.37 mV	0.92 %

PERFORMANCES PARAMETERS DEFINITIONS

Primary current definition:

① Primary current nominal ($I_{P\,N}$)

② Primary current, measuring range ($I_{P\,M}$)
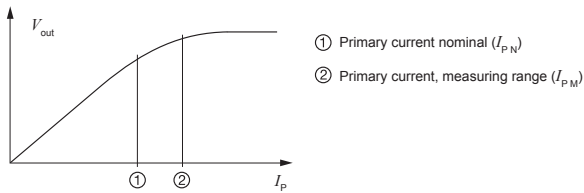
Definition of typical, minimum and maximum values:

Minimum and maximum values for specified limiting and safety conditions have to be understood as such as values shown in "typical" graphs. On the other hand, measured values are part of a statistical distribution that can be specified by an interval with upper and lower limits and a probability for measured values to lie within this interval. Unless otherwise stated (e.g. "100 % tested"), the LEM definition for such intervals designated with "min" and "max" is that the probability for values of samples to lie in this interval is 99.73 %. For a normal (Gaussian) distribution, this corresponds to an interval between −3 sigma and +3 sigma. If "typical" values are not obviously mean or average values, those values are defined to delimit intervals with a probability of 68.27 %, corresponding to an interval between −sigma and +sigma for a normal distribution. Typical, minimum and maximum values are determined during the initial characterization of a product.

Output noise voltage:

The output voltage noise is the result of the noise floor of the Hall elements and the linear amplifier.
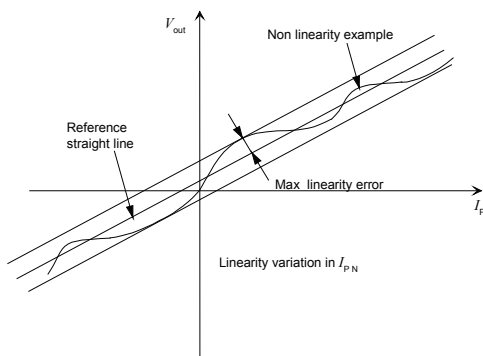
Magnetic offset:

The magnetic offset is the consequence of an any current on the primary side. It's defined after a stated excursion of primary current.
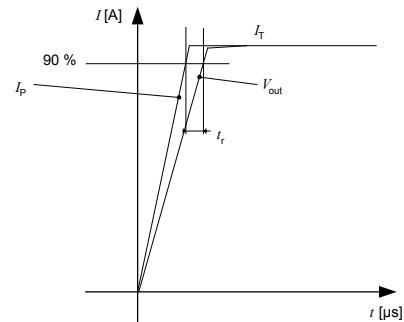
Linearity:

The maximum positive or negative discrepancy with a reference straight line $V_{out} = f(I_P)$.
Unit: linearity (%) expressed with full scale of $I_{P\,N}$.

Response time (delay time) t_r:

The time between the primary current signal ($I_{P\,N}$) and the output signal reach at 90 % of its final value.

Sensitivity:

The transducer's sensitivity G is the slope of the straight line $V_{out} = f(I_P)$, it must establish the relation:

$$V_{out}(I_P) = U_C/5\,(G \times I_P + V_O)$$

Offset with temperature:

The error of the offset in the operating temperature is the variation of the offset in the temperature considered with the initial offset at 25 °C.

The offset variation $I_{O\,T}$ is a maximum variation the offset in the temperature range:

$$I_{O\,T} = I_{O\,E}\,max - I_{O\,E}\,min$$

The offset drift $TCI_{O\,E\,AV}$ is the $I_{O\,T}$ value divided by the temperature range.

Sensitivity with temperature:

The error of the sensitivity in the operating temperature is the relative variation of sensitivity with the temperature considered with the initial offset at 25 °C.

The sensitivity variation G_T is the maximum variation (in ppm or %) of the sensitivity in the temperature range:

G_T = (Sensitivity max − Sensitivity min) / Sensitivity at 25 °C.

The sensitivity drift TCG_{AV} is the G_T value divided by the temperature range. Deeper and detailed info available is our LEM technical sales offices (www.lem.com).

Offset voltage @ I_P = 0 A:

The offset voltage is the output voltage when the primary current is zero. The ideal value of V_O is $U_C/2$. So, the difference of $V_O - U_C/2$ is called the total offset voltage error. This offset error can be attributed to the electrical offset (due to the resolution of the ASIC quiescent voltage trimming), the magnetic offset, the thermal drift and the thermal hysteresis. Deeper and detailed info available is our LEM technical sales offices (www.lem.com).

Environmental test specifications:

Refer to LEM GROUP test plan laboratory CO.11.11.515.0 with "Tracking_Test Plan_Auto" sheet.